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## LETTER TO THE EDITOR

# Integrable non-isospectral flows associated with the Kadomtsev-Petviashvili equations in $2+1$ dimensions 

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#### Abstract

The symmetries of the Kadomtsev-Petviashvili (KP) equations in $2+1$ dimensions yield two hierarchies of integrable non-linear evolution equations (NEE): one is the familiar family of isospectral flows-the KP hierarchy. The other is non-isospectral and its flows have coefficients which depend linearly on $x$ and $y$. The spectral methods used to solve KP can be used to solve all these NEE. An underlying infinite-dimensional Lie algebra is used to determine all the Lax pairs for both families, and it also determines their symplectic structures. Constants of the motion are constructed for the non-isospectral cases.


We take the two KP equations [1-3] in the forms [2-7] $\ddagger$ :

$$
\begin{equation*}
u_{t}=K[u]= \pm \mathrm{D}_{x}^{-1} u_{y y}-6 u u_{x}-u_{x x x} \tag{1}
\end{equation*}
$$

$u_{x} \equiv \partial u / \partial x$, etc; $\mathrm{D}_{x} \equiv \partial / \partial x$ and $\mathrm{D}_{x}^{-1} \equiv \int_{-\infty}^{x} \mathrm{~d} x^{\prime} ;$ KP-I is the positive sign in (1), KP-II is the negative sign. If $u \rightarrow 0$ sufficiently rapdily as $x^{2}+y^{2} \rightarrow \infty$ and $\int_{-\infty}^{\infty} u \mathrm{~d} x=0$, кp-I is solved by a non-local Riemann-Hilbert problem method [4-6]; KP-II is solved by a $\bar{\partial}$ method [5,6]. Both equations are Hamiltonian and are completely integrable in the sense of Liouville-Arnold [7]. There are infinite sets of independent commuting constants $[2,3,7,8]$ and Noether's theorem then suggests there are infinite sets of symmetries leaving the Lagrangian invariant. Two such sets, which we call $K$ - and $\tau$-symmetries, are known $[9,10]$. The first few are [10]:

$$
\begin{align*}
& K_{0}=\frac{1}{3} u_{x} \quad K_{1}=\frac{2}{3} u_{y} \quad K_{2}=K \equiv \mathrm{D}_{x}^{-1} u_{y y}-6 u u_{x}-u_{x x x} \\
& K_{3}=-4 u_{y x x}+\frac{4}{3}\left(\mathrm{D}_{x}^{-1} u_{y y y}\right)-8 u_{x} \mathrm{D}_{x}^{-1} u_{y}+6 u u_{y}  \tag{2}\\
& \tau_{0}=t K_{0}+\sigma_{0} \quad \tau_{1}=t K_{1}+\sigma_{1} \quad \tau_{2}=t K_{2}+\sigma_{2} \tag{3a}
\end{align*}
$$

with

$$
\begin{align*}
& \sigma_{1}=y K_{0} \quad \sigma_{2}=x K_{0}+y K_{1}+\frac{2}{3} u \quad \sigma_{3}=x K_{1}+y K_{2}+\frac{4}{3} \mathrm{D}_{x}^{-1} u_{y} \\
& \sigma_{4}=x K_{2}+y K_{3}-8 u^{2}-4 u_{x x}-2 u_{x} \mathrm{D}_{x}^{-1} u+2 \mathrm{D}_{x}^{-2} u_{y y .} \tag{3b}
\end{align*}
$$

Since the $K$ - and $\tau$-symmetries are symmetries leaving the kp-I equations (1) invariant, they must obviously satisfy the linear variation equation (given here for the $\tau$ )

$$
\begin{equation*}
\tau_{t}=K^{\prime}(\tau) \equiv \lim _{\varepsilon \rightarrow 0} \frac{\partial}{\partial \varepsilon} K[u+\varepsilon \tau] . \tag{4}
\end{equation*}
$$

[^0]$K^{\prime}(\tau)$ is thus the Gateaux derivative of $K$, the functional $K[u]$ of $u$ in (1), in the direction of $\tau$. From the Lie bracket defined as
\[

$$
\begin{equation*}
\llbracket A, B \rrbracket=A^{\prime}(B)-B^{\prime}(A) \tag{5}
\end{equation*}
$$

\]

for any two functionals $A[u], B[u]$ of $u$, the higher-order $K$ - and $\tau$-symmetries are obtained [10] through

$$
\begin{equation*}
K_{n+1}=\frac{3}{n+1} \llbracket K_{n}, \tau_{3} \rrbracket \quad \tau_{n+1}=\frac{3}{n-3} \llbracket \tau_{n}, \tau_{3} \rrbracket \tag{6}
\end{equation*}
$$

with $K_{3}$ from (2) and $n \geqslant 3$, and $\tau_{4}$ from (3) with $n \geqslant 4$. More generally they form the infinite-dimensional Lie algebra [10]

$$
\begin{align*}
& \llbracket K_{m}, K_{n} \rrbracket=0 \quad \llbracket K_{m}, \tau_{n} \rrbracket=\frac{1}{3}(m+1) K_{m+n-2} \\
& \llbracket \tau_{m}, \tau_{n} \rrbracket=\frac{1}{3}(m-n) \tau_{m+n-2} \quad m, n=0,1,2, \ldots \tag{7}
\end{align*}
$$

so the $\sigma_{n}$ (which are not symmetries) satisfy the same algebra with $\sigma_{n}$ replacing $\tau_{n}$. The algebras of the $\sigma_{n}$ or $\tau_{n}$ alone are of Virasoro type [11].

It is proved [12] that there exist $I_{n}, J_{n}$ such that $K_{n}=\mathrm{D}_{x} \delta I_{n} / \delta u, \sigma_{n}=\mathrm{D}_{x} \delta J_{n} / \delta u$ where $\delta / \delta u$ is the functional derivative. The first few of these are

$$
\begin{align*}
& I_{0}=\frac{1}{2} \int u^{2} \mathrm{~d} x \mathrm{~d} y \quad I_{1}=\frac{1}{3} \int\left(u \mathrm{D}_{x}^{-1} \mathrm{D}_{y} u\right) \mathrm{d} x \mathrm{~d} y \\
& I_{2}=\frac{1}{2} \int\left[\left(\mathrm{D}_{x}^{-1} \mathrm{D}_{y} u\right)^{2}+u_{x}^{2}-2 u^{3}\right] \mathrm{d} x \mathrm{~d} y \tag{8}
\end{align*}
$$

and

$$
\begin{align*}
& J_{0}=-\frac{1}{18} \int x u \mathrm{~d} x \mathrm{~d} y \quad J_{1}=\frac{1}{6} \int y u^{2} \mathrm{~d} x \mathrm{~d} y \\
& J_{2}=\int\left(\frac{1}{6} x u^{2}+\frac{1}{3} u y \mathrm{D}_{x}^{-1} \mathrm{D}_{y} u\right) \mathrm{d} x \mathrm{~d} y  \tag{9}\\
& J_{3}=\int\left[\frac{1}{2} y\left(\mathrm{D}_{x}^{-1} \mathrm{D}_{y} u\right)^{2}+\frac{1}{2} u_{x}^{2}-u^{3}+\frac{1}{3} x u \mathrm{D}_{x}^{-1} \mathrm{D}_{y} u\right] \mathrm{d} x \mathrm{~d} y .
\end{align*}
$$

They form an infinite-dimensional Lie algebra isomorphic to (7) through the correspondence [12] $K_{n} \leftrightarrow I_{n}, \tau_{n} \leftrightarrow J_{n}$ and bracket the Poisson bracket. More precisely this arises through the correspondence (the equality) $\llbracket A, B \rrbracket=\mathrm{D}_{x}(\delta\{F, G\} / \delta u)$ with $A=$ $\mathrm{D}_{x}(\delta F / \delta u)$, etc: in both cases the bracket is the usual Poisson bracket $[7,12]\{F, G\}=$ $\int\left[(\delta F / \delta u) \mathrm{D}_{x}(\delta G / \delta u)\right] \mathrm{d} x$ for Kp. Since $I_{2}$ is the Hamiltonian of Kp-I [7, 12], and the $I_{n}$ are (plainly) independent and in involution, $u_{t}=\mathrm{D}_{x}\left(\delta I_{n} / \delta u\right)=K_{n}, n=2,3, \ldots$, form the well known hierarchy of integrable KP-I equations. For the $J_{n}$ one can check that when $u_{t}=K_{2}$ the total derivatives $\mathrm{d}\left(t I_{n}+J_{n}\right) / \mathrm{d} t=0$ and $t I_{n}+J_{n}$ are constants. Likewise if $u_{t}=K_{m}$, then $\frac{1}{3}(m+1) t I_{m+n-2}+J_{n}$ are constants. Even so, one asks whether the equations $u_{t}=\mathrm{D}_{x}\left(\delta J_{n} / \delta u\right)=\sigma_{n}, n=2,3, \ldots$, have significance. The point of this letter is to show that these flows too are integrable flows and can be integrated.

We note that there are also two sorts of symmetries, $K_{n}$ and $\tau_{n}$, for the aKNS systems in $1+1$ dimensions, and Li and Zhu [13] show that $u_{t}=K_{n}$ and $u_{t}=\sigma_{n}$ are isospectral and non-isospectral respectively. The non-isospectral flows have coefficients depending explicitly, but linearly, on $x$-'explaining' previous work [14, 15 and
references therein] $\dagger$ on this feature. The akns systems are a reduction of the kp-I system [17] and apparently KP is more fundamental. In this letter we show the flows $u_{t}=K_{n}$ ( $K_{n}$ from (2)) are the usual isospectral Kp-I hierarchy while flows $u_{t}=\sigma_{N+2}$, $N=n-2$, are non-isospectral and are hierarchies of generalised Kp-I equations with coefficients depending linearly on both $x$ and $y$. It is convenient to introduce the label $N=n-2$ (see below) though $u_{t}=\sigma_{N+2}$ means $u_{t}=\sigma_{n}$.

The flows $u_{\mathrm{t}}=\sigma_{N+2}$ with coefficients depending on $x$ and $y$ are integrable by the same non-local Riemann-Hilbert problem as integrates all of the Kp-I hierarchy $u_{t}=K_{N+2}$. Moreover, unlike the situation for $K d V$ in $1+1$ dimensions, and illustrating the more fundamental nature of the KP system, the flows $u_{t}=\sigma_{N+2}$ are Hamiltonian with infinite sets of commuting constants $\bar{I}_{m}^{(N)}$, different for each $N$, which we give explicitly; there are further quantities $\bar{J}_{m}^{(N)}$, and there are symmetries $\bar{K}_{m}^{(N)}, \bar{\tau}_{m}^{(N)}$ such that $\bar{K}_{m}^{(N)}=\mathrm{D}_{x} \delta \bar{I}_{m}^{(N)} / \delta u, \bar{\tau}_{m}^{(N)}=\mathrm{D}_{x} \delta \bar{J}_{m}^{(N)} / \delta u$. These form a Lie algebra (for fixed $N$ ) [18]:

$$
\begin{array}{lc}
\llbracket \bar{K}_{m}^{(N)}, \bar{K}_{l}^{(N)} \rrbracket=0 & \llbracket \bar{K}_{m}^{(N)}, \bar{\tau}_{l}^{(N)} \rrbracket=\frac{1}{3}(m+1) \bar{K}_{m+l+N}^{(N)}  \tag{10}\\
\llbracket \bar{\tau}_{m}^{(N)}, \bar{\tau}_{l}^{(N)} \rrbracket=\frac{1}{3}(m-l) \bar{K}_{m+l+N}^{(N)} \quad m, l=0,1,2, \ldots
\end{array}
$$

We show in this letter how the eigenspectrum and spectral data for $u_{t}=\sigma_{N+2}$ evolve in time. We also show how the Lie algebras (7) can be used to derive Lax pairs for the flow $u_{t}=K_{N+2}$ and $u_{t}=\sigma_{N+2}$. This is important because the usual integrodifferential operator (familiar as $L^{+}$[2] in $1+1$ dimensions) does not always exist in $2+1$ dimensions in conventional form [19-21]. We give actual examples of some integrable non-isospectral flows in the final part of this letter. We focus on KP-I throughout but note that there is a similar analysis for KP-II although a $\bar{\partial}$ problem is needed to solve these equations.

We will now consider the Lax pairs. The Kp-I equation (1) is the compatibility condition $L_{t}=[B, L]$ on $L \psi=0, \psi_{t}=B \psi$ with the Lax pair [2-7]

$$
\begin{align*}
& L=\frac{1}{3} \mathrm{i} \sqrt{3} \mathrm{D}_{y}+\mathrm{D}_{x}^{2}+u  \tag{11a}\\
& B=-4 \mathrm{D}_{x}^{3}-6 u \mathrm{D}_{x}-3 u_{x}+\mathrm{i} \sqrt{3} \mathrm{D}_{x}^{-1} u_{x} \tag{11b}
\end{align*}
$$

where [, ] is the usual commutator. One checks that $L_{t}=\left[B_{n}, L\right], n=0,1,2,3$ and $L_{t}=\left[C_{n}, L\right], n=1,2,3,4$ are the non-linear evolution equations (NEE) $u_{t}=K_{n}[u]$ and $u_{t}=\sigma_{n}[u]$ respectively when
$B_{0}=\frac{1}{3} \mathrm{D}_{x} \quad B_{1}=\mathrm{i} \frac{1}{3} 2 \sqrt{3}\left(\mathrm{D}_{x}^{2}+u\right) \quad B_{2}=B($ of $(11 b))$
$B_{3}=-i 8 \sqrt{3} D_{x}^{4}-i 16 \sqrt{3} u D_{x}^{2}-\left(i 16 \sqrt{3} u_{x}+8 \mathrm{D}_{x}^{-1} u_{y}\right) D_{x}$

$$
\begin{equation*}
-\left(\mathrm{i} 8 \sqrt{3} u^{2}+\mathrm{i} 8 \sqrt{3} u_{x x}+4 u_{y}-\frac{4}{3} \sqrt{3} \mathrm{i} D_{x}^{-2} u_{y y}\right) \tag{12}
\end{equation*}
$$

$C_{1}=y B_{0}-(\mathrm{i} / 6 \sqrt{3}) x \quad C_{2}=y B_{1}+x B_{0}+\frac{1}{3}$
$C_{3}=y B_{2}+x B_{1}+\frac{1}{3} 2 \mathrm{i} \sqrt{3} \mathrm{D}_{x}+\frac{1}{3} \mathrm{i} \sqrt{3} \mathrm{D}_{x}^{-1} u$
$C_{4}=y B_{3}+x B_{2}-6 \mathrm{D}_{x}^{2}+\frac{2}{3} \mathrm{i} \sqrt{3} \mathrm{D}_{x}^{-1} u_{y} 4 u$.
These operator polynomials are found directly by equating coefficients of powers $\mathrm{D}_{x}$ (note that $\mathrm{D}_{x}^{-1} u_{y}$ is a scalar number not an operator). To proceed further this way
would be impossibly tedious. However, we can find all of the $B_{n}$ and $C_{n}$ from the algebra (7). We define operators $B_{n+1}$, polynomials in $D_{x}$, through

$$
\begin{equation*}
B_{n+1}=\frac{3}{n+1}\left(B_{n}^{\prime}\left(\sigma_{3}\right)-C_{3}^{\prime}\left(K_{n}\right)+\left[B_{n}, C_{3}\right]\right) \quad n \geqslant 3 \tag{13}
\end{equation*}
$$

where $\sigma_{3}$ and $C_{3}$ are given by (3) and (12) respectively. $B_{n}$ is a functional of $u$ so it has a Gateaux derivative $B_{n}^{\prime}$. One proves (13) is a proper definition by induction from $n=3$ as follows. Note that $L_{t}=u_{t}=K_{n}$ and $L_{t}=\left[B_{n}, L\right] \Rightarrow K_{n}=\left[B_{n}, L\right]$, and similarly $C_{n}=\left[C_{n}, L\right]$. Then from (7), with $\sigma_{n}$ for $\tau_{n}$,

$$
\begin{align*}
K_{n+1}=\frac{3}{n+1} & \left(K_{n}^{\prime}\left(\sigma_{3}\right)-\sigma_{3}^{\prime}\left(K_{n}\right)\right) \\
& =\frac{3}{n+1}\left(\left[B_{n}^{\prime}\left(\sigma_{3}\right), L\right]+\left[B_{n}, L^{\prime}\left(\sigma_{3}\right)\right]-\left[C_{3}^{\prime}\left(K_{n}\right), L\right]-\left[C_{3}, L^{\prime}\left(K_{n}\right)\right]\right) . \tag{14}
\end{align*}
$$

Then from $L^{\prime}\left(\sigma_{3}\right)=\sigma_{3}=\left[C_{3}, L\right]$, and similarly, and by using the Jacobi identity for [ , ], one finds $K_{n+1}=B_{n+1}=\left[B_{n+1}, L\right]$ so that $u_{t}=K_{n+1}$ is $L_{t}=\left[B_{n+1}, L\right]$ for $n \geqslant 3$. One proves similarly $C_{m+1}=(3 /(m-3))\left(C_{m}^{\prime}\left(\sigma_{3}\right)-C_{3}^{\prime}\left(\sigma_{m}\right)+\left[C_{m}, C_{3}\right]\right)$ for $m \geqslant 4$ and $u_{t}=\sigma_{n}[u]$ is $L_{t}=\left[C_{n}, L\right]$ for $n=1,2,3, \ldots$.

To apply the non-local Riemann-Hilbert problem method to solve $u_{t}=K_{N+2}$, $u_{t}=\sigma_{N+2}$ we need some other results. The operators $B_{n}, C_{n}$ are polynomials in $\mathrm{D}_{x}$ of degrees $n+1, n$. We assume that under the chosen boundary conditions $B_{n} \rightarrow \bar{B}_{n}$, $C_{n} \rightarrow \bar{C}_{n}$ as $x^{2}+y^{2} \rightarrow \infty$. Then from (13) and its analogue for $u_{t}=\sigma_{n}$ we find

$$
\begin{equation*}
\bar{B}_{n}=b_{n} \mathrm{D}_{x}^{n+1} \quad \bar{C}_{n}=y c_{n} \mathrm{D}_{x}^{n}+x d_{n} \mathrm{D}_{x}^{n-1}+e_{n} \mathrm{D}_{x}^{n-2} \tag{15}
\end{equation*}
$$

where $b_{n}=\frac{1}{3}(2 \mathrm{i} \sqrt{3})^{n}(n \geqslant 0)$, and $c_{n}, d_{n}, e_{n}$ satisfy simple recurrence relations which yield

$$
\begin{equation*}
c_{n}=\frac{1}{3}(2 \mathrm{i} \sqrt{3})^{n-1} \quad d_{n}=\frac{1}{3}(2 \mathrm{i} \sqrt{3})^{n-1} \quad e_{n}=\frac{1}{6}(n-1)(2 \mathrm{i} \sqrt{3})^{n-2} \tag{16}
\end{equation*}
$$

for $n \geqslant 1$, results we use shortly.
We turn now to the solution by the inverse spectral transform and the evolution of the spectral data.

Kp-I is solved by the Riemann-Hilbert problem derived from $L \psi=0$ with $L$ given by (11a) [4, 6]. Thus $u_{t}=K_{n}, n=0,1,2, \ldots$, is solved by the same method. Then, although $u_{t}=\sigma_{N+2}, N+2=1,2, \ldots$, is not isospectral, it is representable by $L_{t}=$ [ $L, C_{n}$ ] so it is solved by the same method. Under the chosen boundary conditions KP-I has lump solutions $[4,6,7]$ and there are both discrete and continuous spectral data. The continuous data $f(k, l, t)$ satisfy $[4,6]$

$$
\begin{equation*}
\psi^{+}(k)=\psi^{-}(k)+\int_{-\infty}^{\infty} \psi^{-}(l) f(k, l ; t) \mathrm{d} l \tag{17}
\end{equation*}
$$

where $\psi^{ \pm}(k)$ solve $L \psi^{ \pm}(k)=0$ : they satisfy $[4,6] \exp \left[-\mathrm{i}\left(k x-\sqrt{3} k^{2} y\right)\right] \psi^{ \pm} \equiv \mu^{ \pm} \sim 1$ as $x^{2}+y^{2} \rightarrow \infty$ and $\mu^{ \pm}$can be analytically continued from the real $k$ axis into the upper and lower half $k$ planes respectively. The functions $\mu^{ \pm}$satisfy a Fredholm equation of the second kind with Green functions derived from $L \psi^{ \pm}=0$, i.e. from ( $\mathrm{D}_{x}^{2}+k^{2}+$ $\left.\mathrm{D}_{y}\right) G=-\delta(x) \delta(y)$ (refer to equations (7) (there given for $n=2$ ) and (5) of [6]). Simple poles in the eigenfunction $\mu^{ \pm}$at $k=k_{j}^{ \pm}$determine lump solutions [4, 6]. Then discrete data $\gamma_{j}$ are defined through $[4,6]$ :

$$
\begin{equation*}
\lim _{k \rightarrow k_{j}^{ \pm}}\left(\mu^{ \pm}-\mathrm{i} \psi_{j}^{ \pm}(x, y)\left(k-k_{j}^{ \pm}\right)^{-1}\right)=\left[x-2 \sqrt{3} k_{j}^{ \pm} y+\gamma_{j}^{ \pm}\right] \psi_{j}^{ \pm}(x, y) \tag{18}
\end{equation*}
$$

the residues $\psi_{j}^{ \pm}$are homogeneous solutions corresponding to $k_{j}^{ \pm}$of the Fredholm equation normalised by $\left(x-2 \sqrt{ } 3 k_{j}^{ \pm}\right) \psi_{j}^{ \pm} \rightarrow 1$ as $\left(x^{2}+y^{2}\right)^{1 / 2} \rightarrow \infty$.

A complete set of spectral data $S$ is [4-6] $S=\left\{f(k, l ; t) ; k_{j}^{ \pm}, \gamma_{j}^{ \pm}, 1 \leqslant j \leqslant M\right\}$. For its time evolution we first add a scalar multiple $\beta_{n}(k)$ of the identity to $B_{n}: \beta_{n}(k)$ is then essentially the linearised dispersion relation (as usual). Thus we set

$$
\begin{equation*}
L_{n}(k) \psi \equiv\left(D_{t}-B_{n}+\beta_{n}(k)\right) \psi=0 \tag{19}
\end{equation*}
$$

and since $\psi^{ \pm}=\left\{\exp \mathrm{i}\left(k x-\sqrt{3} k^{2} y\right)\right\} \mu^{ \pm}$, and $\mu^{ \pm} \sim 1, B_{n} \sim \bar{B}_{n}$ as $x^{2}+y^{2} \rightarrow \infty, \beta_{n}(k)=$ $(\mathrm{i} / 6 \sqrt{ } 3)(-2 \sqrt{ } 3 k)^{n+1}$. Then, by applying $L_{n}(k)$ to (17) and using $L_{n}(k)-\beta_{n}(k)=$ $L_{n}(l)-\beta_{n}(l)$ we readily find

$$
\begin{equation*}
f_{t}(k, l)=(\mathrm{i} / 6 \sqrt{3})\left((-2 \sqrt{3} k)^{n+1}-(-2 \sqrt{3} l)^{n+1}\right) f(k, l) \tag{20}
\end{equation*}
$$

while in a similar way we find

$$
\begin{equation*}
k_{j, t}^{ \pm}=0 \quad \gamma_{j, t}^{ \pm}=\frac{1}{3}(n+1)\left(-2 \sqrt{3} k_{j}^{ \pm}\right)^{n} \quad j=1, \ldots, M . \tag{21}
\end{equation*}
$$

Results (20) and (21) coincide for $n=2$ with those derived for KP-I [4, 6].
For the time evolution of the scattering data for $u_{t}=\sigma_{N+2}$ we define $L_{n}(k)$ through

$$
\begin{equation*}
L_{n}(k) \psi \equiv\left(D_{t}-C_{n}+\alpha_{n}(k)\right) \psi=0 \tag{22}
\end{equation*}
$$

From the asymptotics of $\psi^{ \pm}$and $C_{n} \sim \bar{C}_{n}$ as $x^{2}+y^{2} \rightarrow \infty$ we then find

$$
\begin{equation*}
k_{t}=(-1 / 6 \sqrt{3})(-2 \sqrt{3} k)^{n-1} \tag{23}
\end{equation*}
$$

for all $k$ in the $k$ plane while $\alpha_{n}(k)=-\frac{1}{6}(n-1)(-2 \sqrt{3} k)^{n-2}$. Consequently

$$
\begin{equation*}
\mathrm{d} f / \mathrm{d} t \equiv \frac{1}{2}(n-1)^{\frac{1}{3}}\left[(-2 \sqrt{3} k)^{n-2}-(2 \sqrt{3} l)^{n-2}\right] f(k, l) \tag{24}
\end{equation*}
$$

where $\mathrm{d} f / \mathrm{d} t \equiv f_{t}+f_{k} k_{t}+f_{l} l_{t}$ and $k_{t}$ is given by (23): $l_{t}$ is (23) with $l$ replacing $k$.
For the discrete data we use (18). Equation (22) for $\psi^{ \pm}$is an equation for the $\mu^{ \pm}$ and thus for the residues $\psi_{j}^{ \pm}$at their poles $k_{j}^{ \pm}$. For large $x, y(22)$ means $\bar{L}_{n}(k) \sim 0$ where

$$
\begin{gather*}
\bar{L}_{n}(k)=D_{t}-y c_{n} \sum_{\substack{m=0 \\
n-2}}^{n}\binom{n}{m}(\mathrm{i} k)^{n-m} \mathrm{D}_{x}^{m}-x d_{n} \sum_{m=0}^{n-1}\binom{n-1}{m}(\mathrm{i} k)^{n-m+1} \mathrm{D}_{x}^{m} \\
-e_{n} \sum_{m=1}^{n-2}\binom{n-2}{m}(\mathrm{i} k)^{n+m-2} \mathrm{D}_{x}^{m} \tag{25}
\end{gather*}
$$

with $c_{n}, d_{n}, e_{n}$ from (16). Then, since from (18) $\lim _{k \rightarrow k_{j}^{ \pm}}\left(k-k_{j}^{ \pm}\right) \mu^{ \pm}=\psi_{j}^{ \pm}$, application of $\bar{L}_{n}$ to this result followed by execution of the actual limit $k \rightarrow k_{j}^{ \pm}$yields

$$
\begin{equation*}
\bar{L}_{n}\left(k_{j}^{ \pm}\right) \psi_{j}^{ \pm}=\lim _{k \rightarrow k_{j}^{ \pm}} \frac{k_{\mathrm{t}}-k_{j, t}^{ \pm}}{k-k_{j}^{ \pm}} \psi_{j}^{ \pm}=\frac{1}{3}(n-1)\left(-2 \sqrt{3} k_{j}^{ \pm}\right)^{n-2} \psi_{j}^{ \pm} \tag{26}
\end{equation*}
$$

after using (23) for $k_{t}$ and $k_{j, t}$. Finally we apply $\bar{L}_{n}(k)$ to (18) itself; use (25) and (26), and take the limit $k \rightarrow k_{j}^{ \pm}$to find that (18) reduces to $\bar{L}_{n}\left(k_{j}^{ \pm}\right)\left(x-2 \sqrt{3} k_{j}^{ \pm}+\gamma_{j}^{ \pm}\right)$, so that, by using (26)

$$
\begin{equation*}
\gamma_{j, 1}^{ \pm}+\frac{1}{3}(n-1)\left(-2 \sqrt{3} k_{j}^{ \pm}\right)^{n-2} \gamma_{j}^{ \pm}=-\frac{1}{3}(n-1)(n-2)\left(-2 \sqrt{3} k_{j}^{ \pm}\right)^{n-3} . \tag{27}
\end{equation*}
$$

We thus have the time evolution of the spectral data $S$ for $u_{t}=\sigma_{N+2}, n=N-2=$ $1,2, \ldots$; if these equations can be solved the data $S$ can be inverted (at fixed $t$ ) exactly as in the isospectral case.

By continuation so that $y \rightarrow-\mathrm{i} y \mathrm{KP}-\mathrm{I}$ becomes Kp-II. For the latter it is therefore sufficient to replace $y$ by $-\mathrm{i} y$ at each point of the analysis to (16). Then, although the method of solution becomes a $\bar{\partial}$ problem [5,6] and data $T_{1}(k)$ [6] replace $f(k, l)$ and there are no discrete data (while $\mu$ and $\psi$ are nowhere analytic and have no continuation), the present analysis is little changed. One finds

$$
\begin{equation*}
\mathrm{d} T_{1} / \mathrm{d} t=\frac{1}{2}(n-1) \frac{1}{3}\left[(-2 \sqrt{3} k)^{n-2}-(2 \sqrt{3} \bar{k})^{n-2}\right] T_{1} \quad n \geqslant 1 \tag{28}
\end{equation*}
$$

where $\mathrm{d} T_{1} / \mathrm{d} t=T_{1, t}+T_{1, k} k_{t}+T_{1, \bar{k}} \bar{k}_{t} ; k=k_{\mathrm{R}}+\mathrm{i} k_{\mathrm{I}}, \bar{k}=k_{\mathrm{R}}-\mathrm{i} k_{\mathrm{I}}$ and $k_{t}, \bar{k}_{t}$ are (23) in terms of $k$ or $\bar{k}$.

We now consider the symplectic structure and constants of the motion, returning to KP-I and its hierarchies. The $I_{n}$ of (8) are constants for $u_{t}=K_{n}$. The constants for $u_{t}=\sigma_{n}$ are constructed as follows [18]. We define

$$
\begin{equation*}
F_{n}(\lambda, t) \equiv \lambda^{n}\left(1+\frac{1}{3} N t \lambda^{N}\right)^{-(n+1) / N}=\sum_{m=0}^{\infty} f_{n m} \lambda^{n+N m} \tag{29}
\end{equation*}
$$

for $n=0,1,2, \ldots: N \geqslant-1$ is a fixed integer to be identified with $n-2$; the $f_{n m}$ depend on $t ; \lambda \equiv(-2 \sqrt{3} k)$. One checks

$$
\begin{equation*}
f_{n 0}=1 ; f_{n m+1, t}+\frac{1}{3}(n+N m+1) f_{n m}=0 \tag{30}
\end{equation*}
$$

and if $\bar{I}_{n} \equiv \sum_{m=0}^{\infty} f_{n m} I_{n+N m}, n=0,1,2, \ldots$, one finds

$$
\begin{equation*}
\frac{\mathrm{d} \bar{I}_{m}}{\mathrm{~d} t}=\frac{\partial}{\partial t} \bar{I}_{m}+\left\{\bar{I}_{m}, J_{N+2}\right\}=0 \tag{31a}
\end{equation*}
$$

while

$$
\begin{equation*}
\left\{\bar{I}_{m}, \bar{I}_{n}\right\}=0 \quad m, n=0,1,2, \ldots \tag{31b}
\end{equation*}
$$

Thus the $\bar{I}_{m}$ are constants with respect to the Hamiltonian $J_{n+2}$ and the flow $u_{t}=$ $\mathrm{D}_{x} \delta J_{N+2} / \delta u=\sigma_{N+2}$. They are in involution, and since $N \geqslant-1$ is an arbitrary integer there are distinct countably infinite sets of $\bar{I}_{m}$ for each $N$ and each flow $u_{t}=\sigma_{N+2}$. This does not (quite) prove $u_{t}=\sigma_{N+2}$ is completely integrable. But the $I_{n}$ can be expressed in terms of scattering data [7] and for each $N$ the $\bar{I}_{n}$ therefore can be. We then find the $\bar{I}_{n} \equiv \bar{I}_{n}^{(N)}$ can be expressed in terms of action-type variables alone with a determinable time evolution. We give the details elsewhere (some details are in [18]) and show there also that there are the further quantities $\bar{J}_{m}^{(N)}$ and symmetries $\bar{K}_{m}^{(N)}$, $\bar{\tau}_{m}^{(N)}$ of $u_{t}=\sigma_{N+2}$ satisfying the Lie algebra (10) mentioned earlier in this letter. We should note that $N=n-2$ only becasue we work from $K p-I$ with symmetry $K \equiv K_{2}$ : from $K \equiv K_{m}$ we derive flows $u_{t}=\tau_{(n-m)+m}$ and $N=n-m$. However, the $\bar{J}_{m}^{(N)}$ are linear combinations of the $I_{n}$ and satisfy a relation like that for the $\bar{I}_{m}^{(\mathcal{N})}$. Thus there is no point in pursuing flows and symmetries $u_{t}=\bar{K}_{m}^{(N)}, u_{t}=\bar{\tau}_{m}^{(N)}$ for each $N$ as (10) suggests. There are thus the flows $u_{t}=K_{n}$ and $u_{t}=\sigma_{n}$, and only these, of independent significance. We complete this letter with some examples.

A general set of integrable nee is evidently

$$
\begin{equation*}
u_{t}=\sum_{n=0}^{M} \omega_{n} K_{n}+\sum_{n=1}^{M} \bar{\omega}_{n} \sigma_{n} \tag{32}
\end{equation*}
$$

with Lax operator $L$ given by (11a) and $B$ given by $B=\sum_{n=0}^{M} \omega_{n} B_{n}+\sum_{n=1}^{M^{\prime}} \bar{\omega}_{n} C_{n}$. These NEE are solved by the spectral method sketched earlier in this letter and the spectrum evolves as $\lambda_{t}=\frac{1}{3} \Omega(\lambda) ; \Omega=\sum_{n=1}^{M^{\prime}} \bar{\omega}_{n} \lambda^{n-1}$ with $\lambda \equiv-2 \sqrt{3} k$. More particularly consider

$$
\begin{align*}
u_{t} & =K_{2}+\alpha \sigma_{1}+\beta \sigma_{2} \\
& =\mathrm{D}_{x}^{-1} u_{y y}-6 u u_{x}-u_{x x x}+\frac{1}{3} \alpha y u_{x}+\beta\left(\frac{1}{3} x u_{x}+\frac{2}{3} y u_{y}+\frac{2}{3} u\right) \tag{33}
\end{align*}
$$

in which $\alpha, \beta$ are constants. The Lax pair operator is $B=B_{2}+\alpha C_{1}+\beta C_{2}$, and the time evolution of the spectral data is

$$
\begin{align*}
& \left(-2 \sqrt{3} k_{j}^{ \pm}\right)_{t}=\frac{1}{3} \alpha+\frac{1}{3} \beta\left(-2 \sqrt{3} k_{j}^{ \pm}\right) \\
& \gamma_{j, t}^{ \pm}=12 k_{j}^{ \pm}-\frac{1}{3} \beta \gamma_{j}^{ \pm}  \tag{34}\\
& f_{t}=4 \mathrm{i}\left(l^{3}-k^{3}\right) f+(6 \sqrt{3})^{-1} \alpha\left(f_{k}+f_{l}\right)-\frac{1}{3} \beta\left(k f_{k}+l f_{l}\right)
\end{align*}
$$

Moreover the Hamiltonian is $H=I_{2}+\alpha J_{1}+\beta J_{2}$ (determined by (8) and (9)) and the constants of the motion are

$$
\begin{equation*}
\bar{I}_{n}=\exp \left[-\frac{1}{3} \beta(n+1) t\right] \sum_{m=1}^{n+1}\binom{n+1}{m} \alpha^{n+1-m} \beta^{m} I_{m-1} \tag{35}
\end{equation*}
$$

Further details of the results given in this letter as well as some of their generalisations mentioned will be given elsewhere.

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Note added in proof. In connection with the Virasoro type algebras of (7) and (10), it has been shown [22] that symmetries like the $\tau_{m}$ in $1+1$ dimensions can be realised as infinitesimal conformal transformations of the spectral problem: no equivalent result for the KP equations (which are also discussed) was reported.

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    $\ddagger$ It is here convenient to take the scaling of KP as in [8] rather than as in, e.g., [10].

